

THREE INDEPENDENT AXES – 25 mm ORTHOGONAL TRAVEL IN X, Y AND Z

SOFTWARE-BASED DIAGONAL AXIS IN ANY USER SELECTABLE ANGLE (0 - 90 DEGREES)

SUB-MICRON (LESS THAN 100 mm) RESOLUTION

FAST MOVEMENT WITH A TOP SPEED OF 3 mm/sec (WHILE HOMING)

MECHANICALLY ROBUST CONSTRUCTION FOR HIGH STABILITY

COMPACT, FANLESS, USER-FRIENDLY, ROE CONTROLLER PRESERVES BENCH AND RACK SPACE

**CARRIES UP TO A KILOGRAM** 

MULTIPLE PUSH BUTTON FUNCTIONS – WORK, HOME, LOCK, PULSE, RELATIVE, SPEED & ANGLE

SUITED FOR IN VIVO AND IN VITRO ELECROPHYSIOLOGICAL RECORDING



## TRIO -- 235 THREE-AXIS MICROMANIPULATOR SYSTEM

Ideal for in-vivo work, the **TRIOTM-235**, replaces the Z-axis and replaces it with an adjustable diagonal axis. This configuration pairs a traditional X and Y-axis with a diagonal axis that can be adjusted in angle with a set screw. The diagonal features 50 mm of travel, with 25 mm of travel in the X and Y-axes. On this model, we have added software to create a synthetic "Z-axis" by combining the Diagonal and X-axes in reverse of how we create a synthetic diagonal axis on our other manipulators. The **TRIO-235** features a precision bearing and lead-screw design.

The **TRIO-235** controller employs a combination of state-of-the-art software and mechanical design that eliminates the need for the motor to remain powered on during recording, thus eliminating the heating effects of the motors and giving us the electrically quietest manipulators in the industry. This stability ensures that Sutter manipulators will not drift in the middle of experiements.

The compact design of the integrated Rotary Optical Encoder (ROE) controller uses minimal bench space; provides quiet, fan-free operation; and is easy to use. No rack mounted controller is required. Position coordinates, in relative or absolute values, are

displayed directly on the ROE. The TRIO manipulators use a logarithmic acceleration algorithm that eliminates the need for speed selection. As the knobs on the ROE are turned faster, acceleration ramps up. This allows for smooth and intuitive motion control of electrode position without the need to stop and change speeds or lift your hand from the knobs. A Y-axis lockout function (accessible by DIP switch) is also available, allowing X/Diagonal-only axial movement during HOME and WORK repositioning.

Five conveniently located buttons control all the functions you will need in normal operation. Press and hold the [WORK] button to guickly store a work position; pressing [WORK] after this will return the manipulator to the same location. [HOME] sends the manipulator to a second position, often set for a point furthest from the microscope, which is useful for rapid pipette exchange. Pressing [SPEED] allows the selection of one of 4 speed ranges. With practice, there is no need to ever change speeds, however, we have included three low speed ranges for those who work at very high magnification. Holding [SPEED] for three-seconds will lock the knobs out, to prevent accidental movement. Display coordinates can toggle between relative and absolute by pressing the [RELATIVE] button; holding the button

down will zero the relative coordinates. Finally, [PULSE] activates a pulse movement mode that produces small, rapid bursts of motion that can be advantageous for cell penetration with sharp electrodes. Hold [PULSE] for three-seconds to set or modify the angle the diagonal axis is positioned at. This allows the controller to calculate the synthetic "Z-Axis".

Designed with maximum flexibility in mind, a DIP switch on the controller changes the directional movement of the ROE knobs to accommodate the preference of the user. The **TRIO-235** comes standard with a universal mounting system suitable for the most popular headstages or pipette holders.

## TRIO™-235 BASIC SYSTEM

Includes the manipulator, controller, rod holder, 4 inch dovetail extension, mounting adapter plate, Z-axis vertical extension, cables, and power supply

**TRIO-235** 3-axis manipulator (X,Y and diagonal)



SUTTER INSTRUMENT